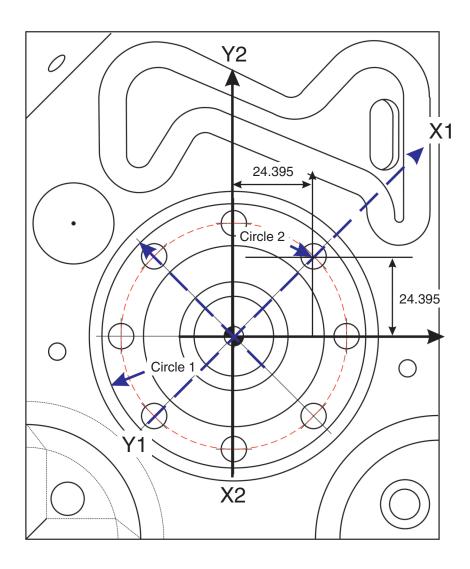
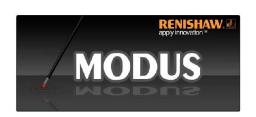


Part alignment - plane and two circles (one offset) (non-CAD)



X1 - Y1: Coordinate system through the two holes.

X2 - Y2: Coordinate system corrected via rotation.



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Renishaw part no: H-1000-5314-01-B

Issued: 12 2014

Part alignment - plane and two circles (one offset) (non-CAD)

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1 Part alignment - plane and two circles (one offset) (non-CAD)

1.1 Tutorial pre-requisites

- The student should be familiar with the 'Principles of part alignment'
- The student should have covered 'Part alignment plane, line and point' and 'Part alignment plane and two circles'

1.2 Tutorial objectives

- Further exposure to feature measurement and constructions
- Introduction to datum manipulation rules and practical application

2 Introduction

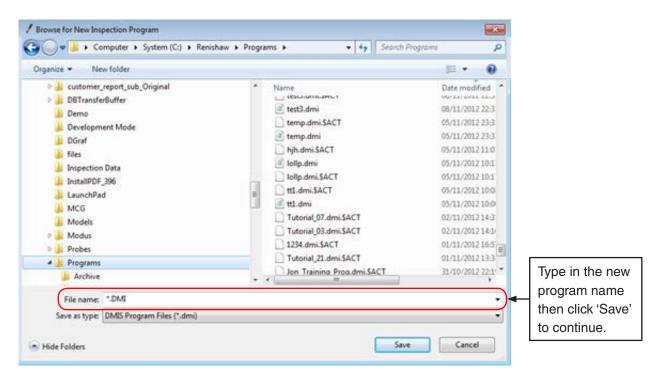
This tutorial introduces the student to a practical scenario where drawing datum requirements cannot be directly transposed from feature definitions, i.e. boxed ("reference" or "basic") dimensions are applied.

3 Create a new program

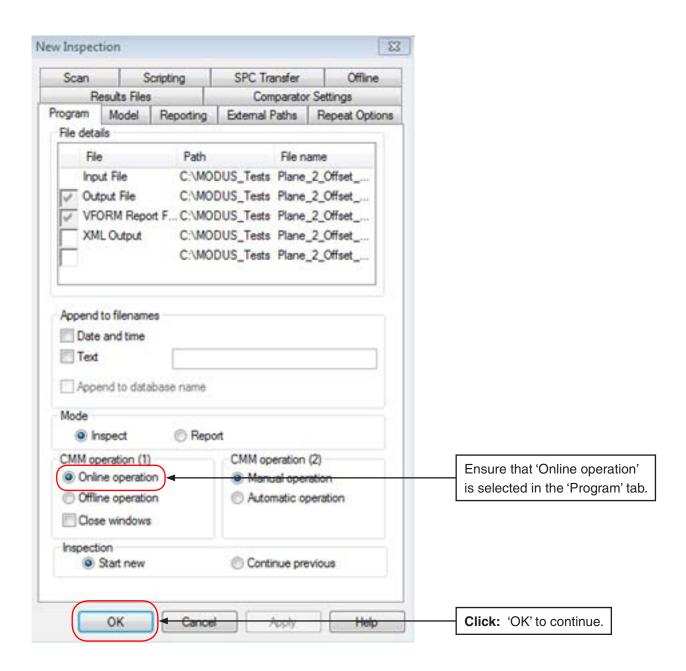




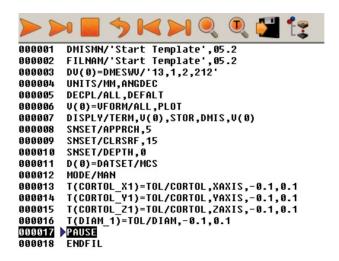
After clicking 'Browse' select a suitable location for the program:





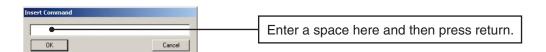


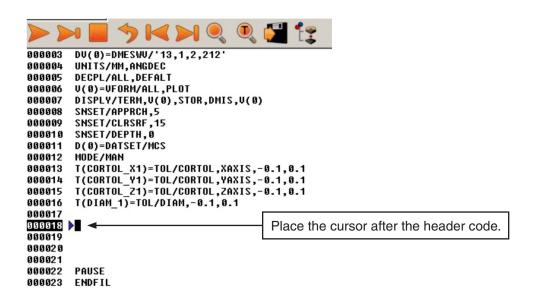
The following header will be inserted into the program:



Insert some line spaces to make the program easier to read. Press

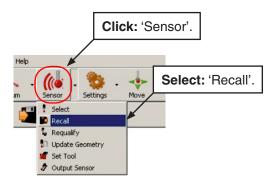




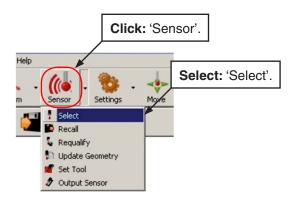


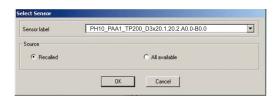
The sensor that is to be used needs to be recalled and selected.

Recall the tool by clicking 'Sensor' then selecting 'Recall':



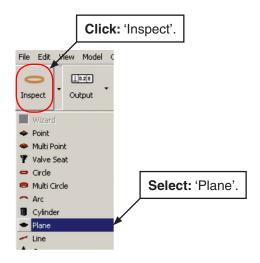




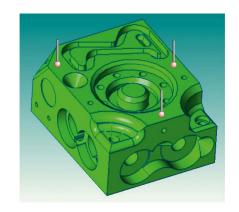


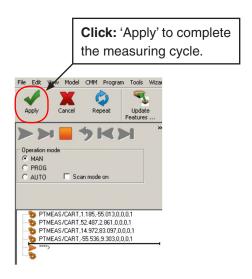
```
000012
         MODE/MAN
         T(CORTOL_X1)=TOL/CORTOL,XAXIS,-0.1,0.1
T(CORTOL_Y1)=TOL/CORTOL,YAXIS,-0.1,0.1
T(CORTOL_Z1)=TOL/CORTOL,ZAXIS,-0.1,0.1
000013
000014
000015
         T(DIAM_1)=TOL/DIAM,-0.1,0.1
000016
                                                                                         The program will now have
000017
                                                                                         two additional lines which
000018
         RECALL/SA(PH10_PAA1_TP200_D3x20.1.20.2.A0.0-B0.0) •
000019 SI
000026 >
         SNSLCT/SA(PH10_PAA1_TP200_D3x20.1.20.2.A0.0-B0.0) -
                                                                                         recall and select the tool.
000021
000022
000023
         PAUSE
000024
         ENDFIL
```

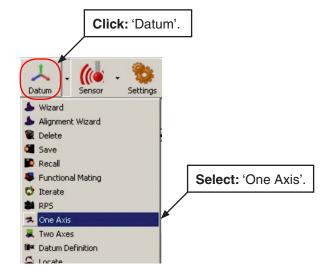
4 Measure a plane and two circles

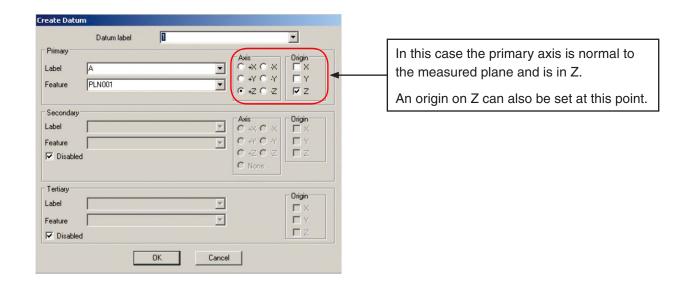


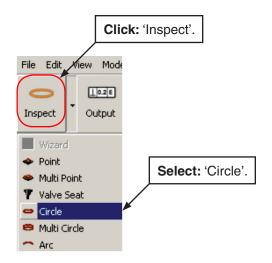
Take a minimum of three points on the plane:



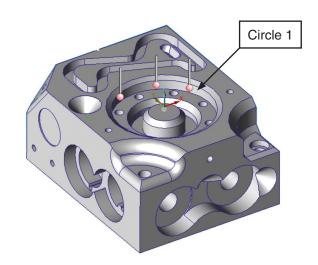


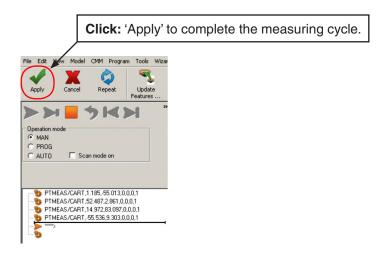


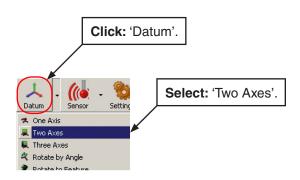


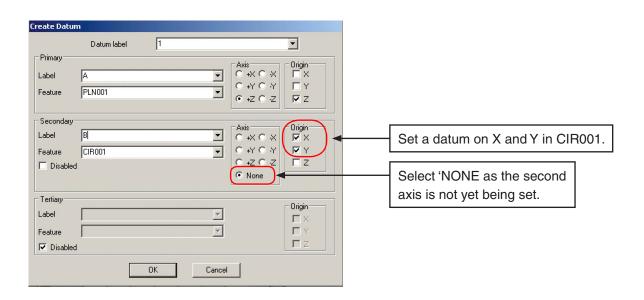


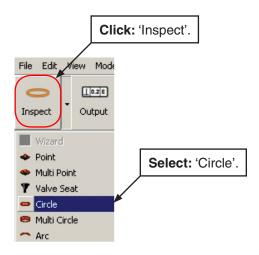
Take a minimum of three points in circle 1



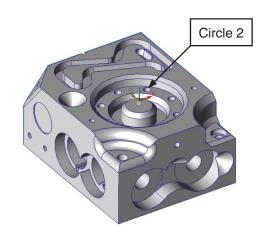


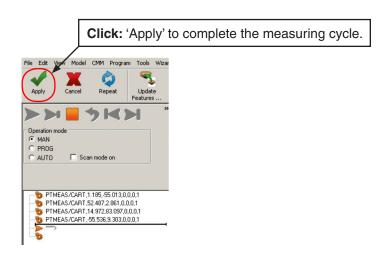




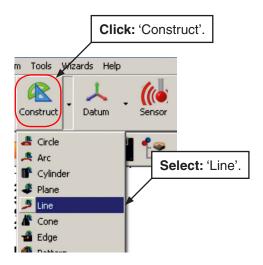


Take a minimum of three points in circle 2.

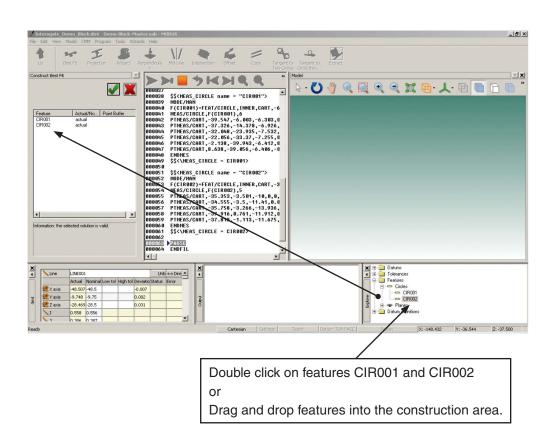




5 Construct a line from measured data



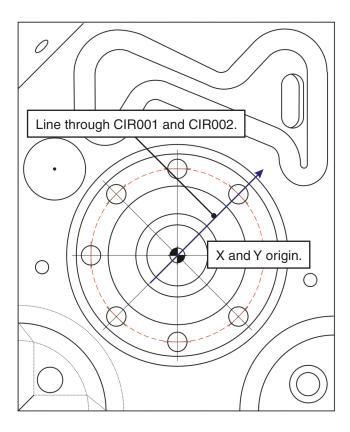


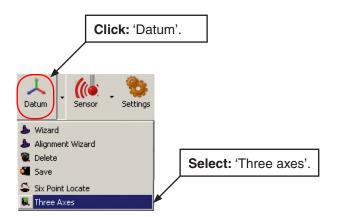


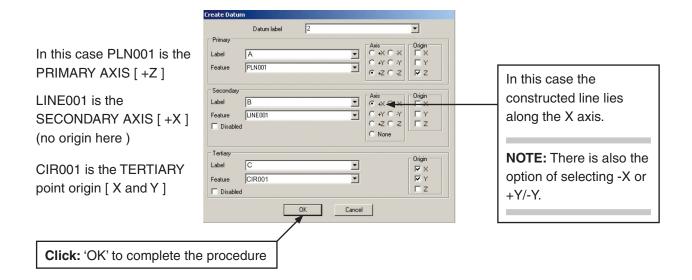
Click: 'Apply' to complete the construction cycle.

Code Produced :-

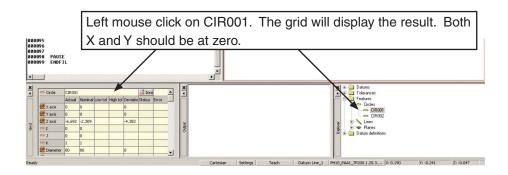
F(LINE001)=FEAT/LINE,UNBND,CART,57.5,20.13,-40,0,-1,0,-1,0,0 CONST/LINE,F(LINE001),BF,FA(CIR001),FA(CIR002)

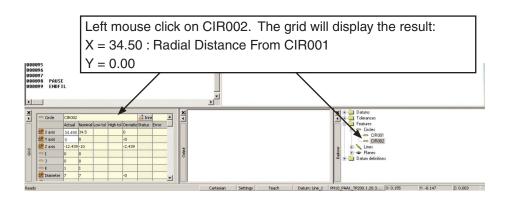




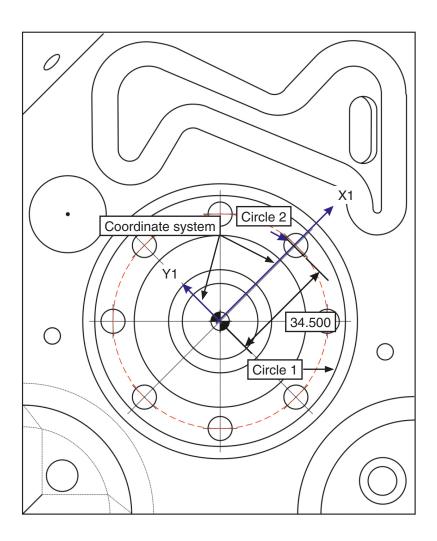


Now check if both circles are in the correct positions:





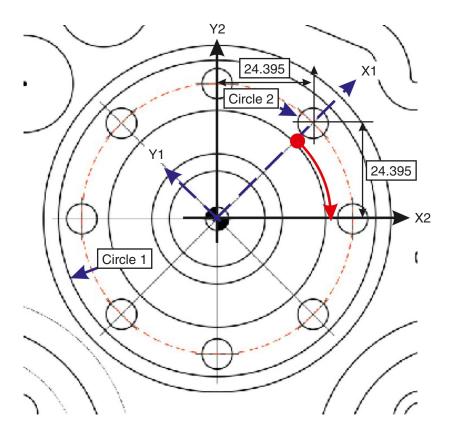
6 Rotate co-ordinate system by angle



Now make a theoretical rotation using the defined angle through the two co-ordinates given i.e:-

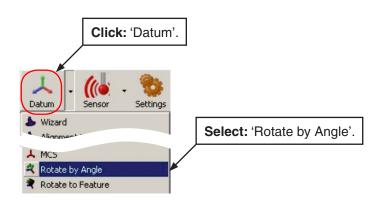
X = 24.395 and Y = 24.395

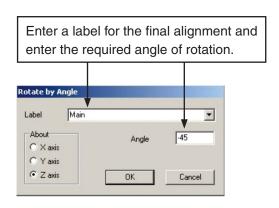
Angle = Inv Tan (24.395 / 24.395) = 45°



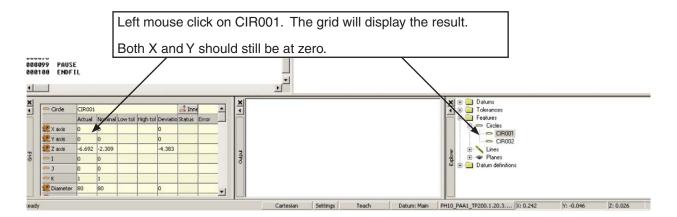
In this case the X and Y axes are to be rotated clockwise by 45°.

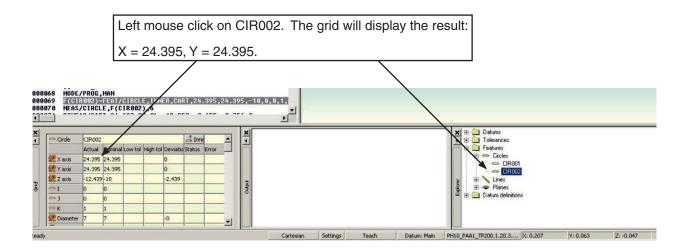
NOTE: -ve angles give clockwise rotation, +ve angles give anti-clockwise rotation.





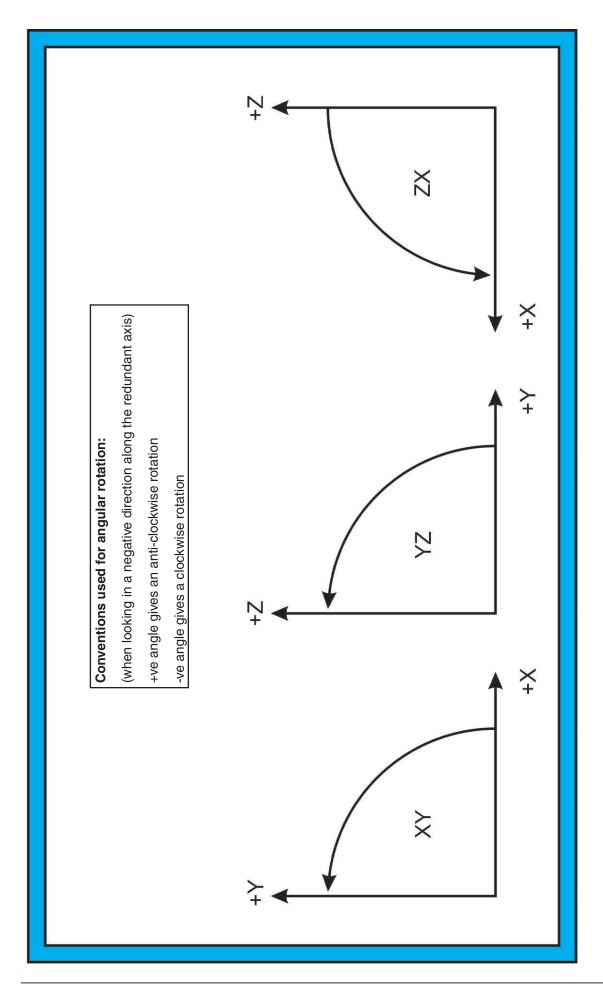
Now check if both circles are in the correct positions:

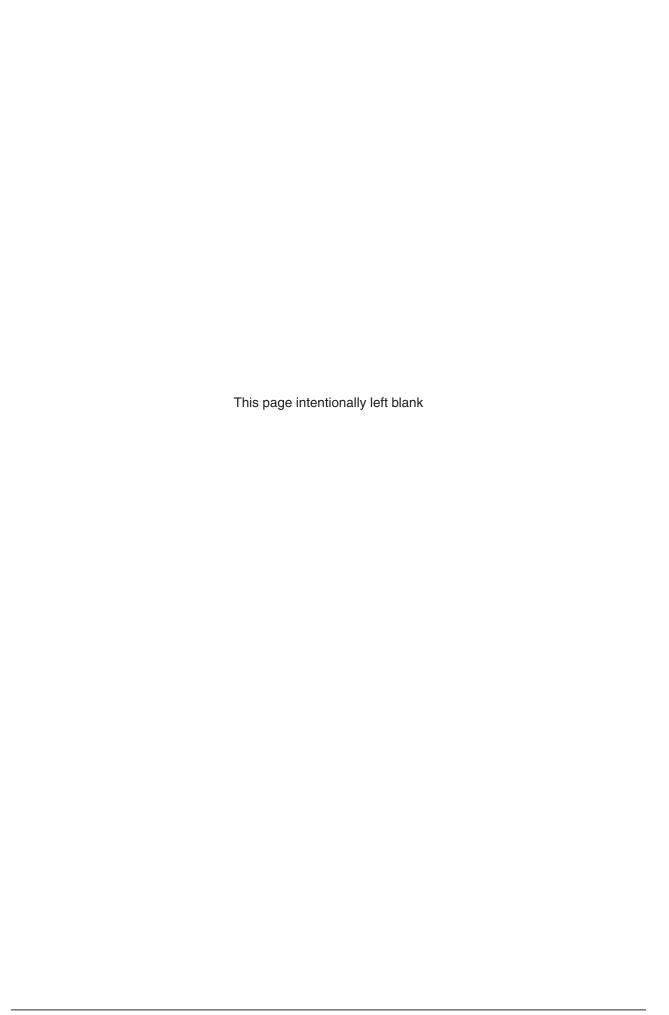




The part alignment is now complete and is ready for measurement.

GUIDANCE NOTE: This is a very basic manual alignment using reduced points and is not accurate enough for good metrology.





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